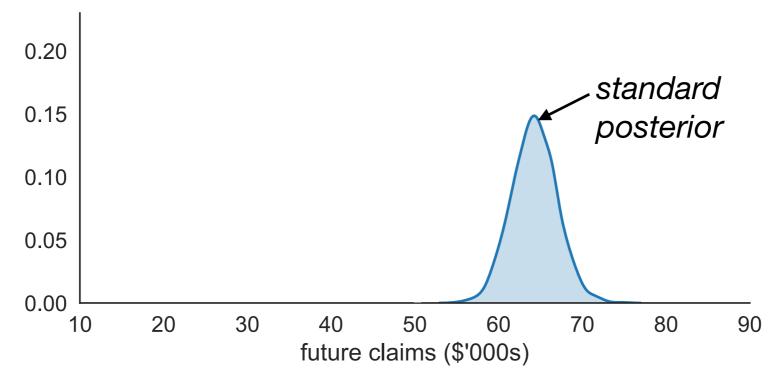
Using Bagged Posteriors for Robust Inference

Jonathan Huggins Harvard University

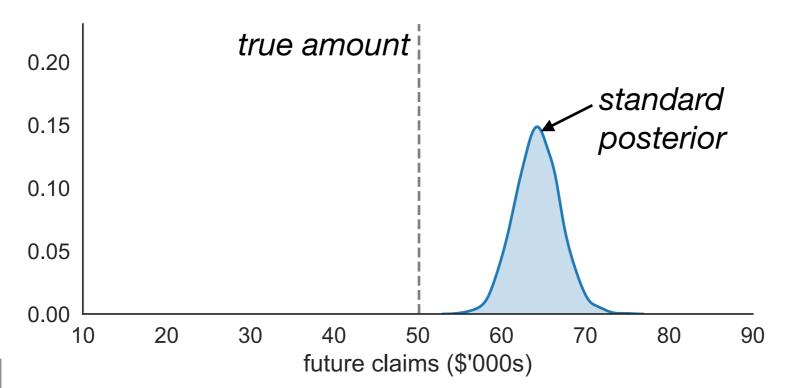
Joint work with Jeff Miller

• Goal: predict future insurance claims based on (real) historic data

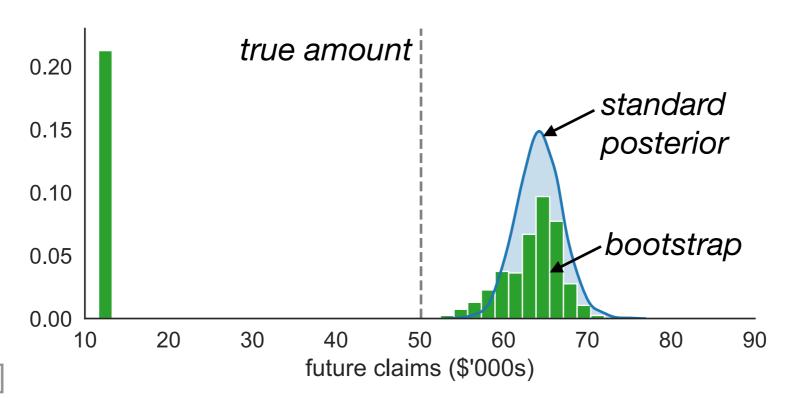
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- Try Bayesian inference with (non-trivial) model (data is 10 time series)



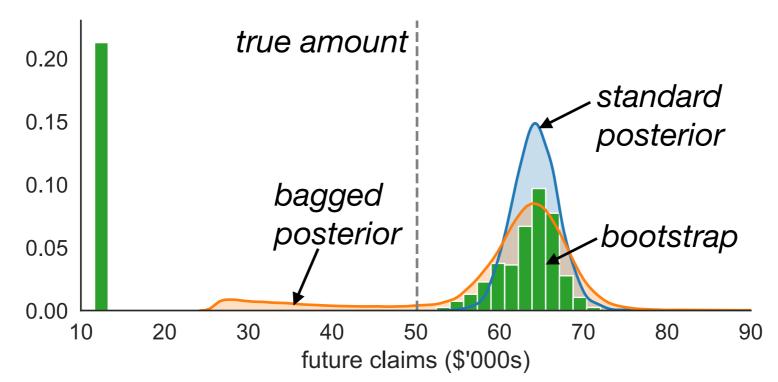
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- Alternative: the bootstrap ⇒ too little data
- Solution: use the bagged posterior (BayesBag)

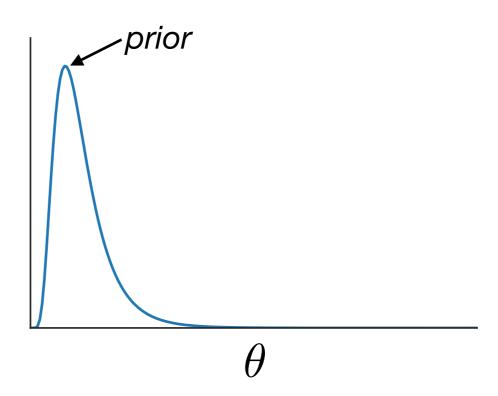


Agenda

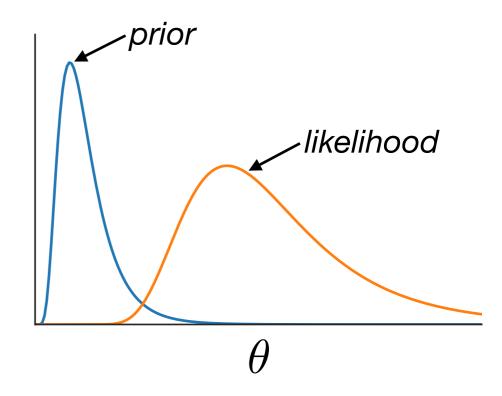
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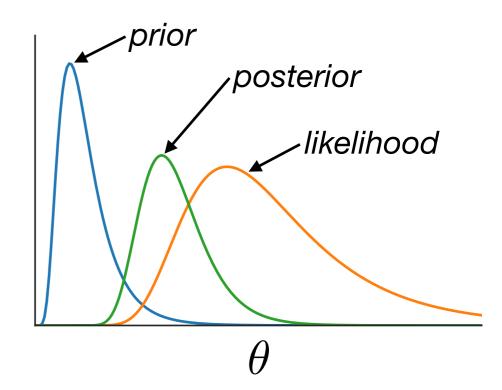


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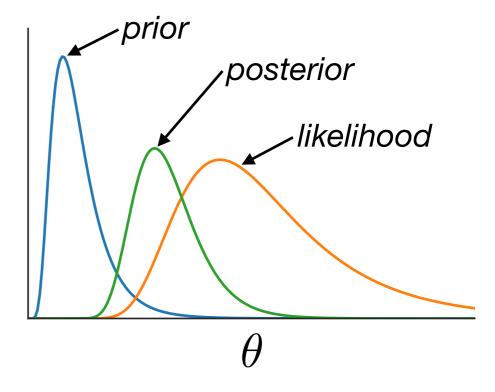
$$\pi(\theta \mid Y) \propto p(Y \mid \theta)\pi_0(\theta)$$



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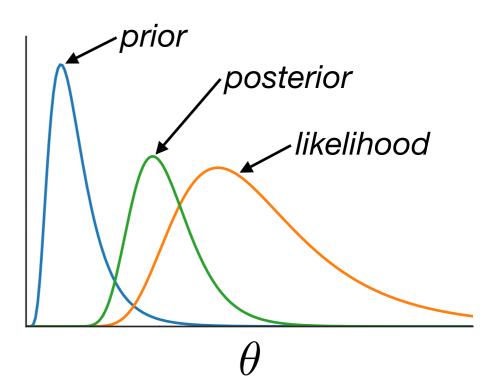
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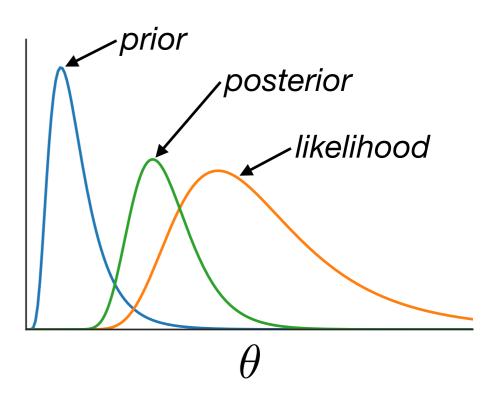
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- **Assumption #1:** measurement model correct: observed Y has distribution $p(Y \mid \theta_{\text{true}})$

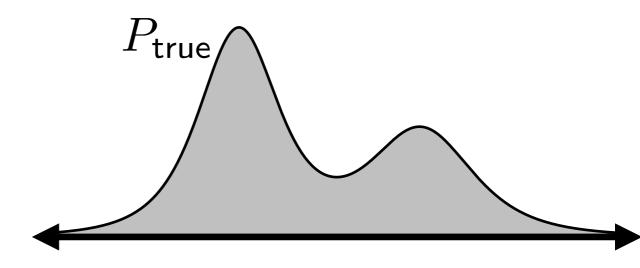


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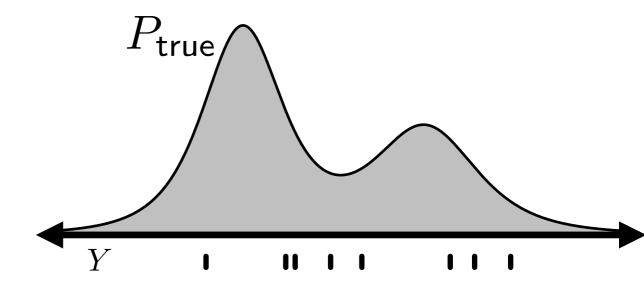
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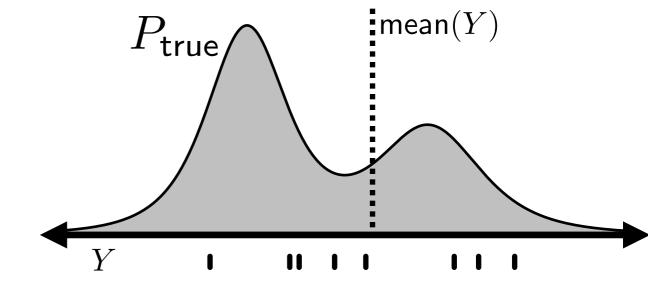




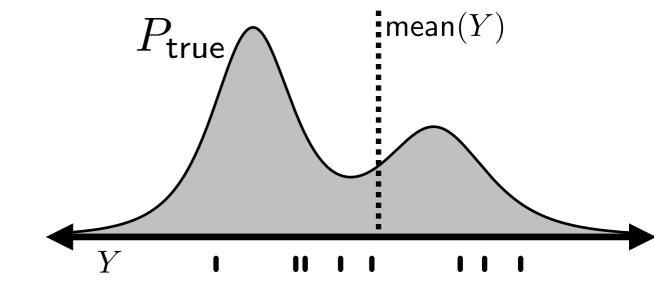
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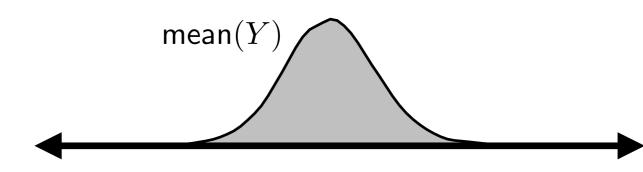
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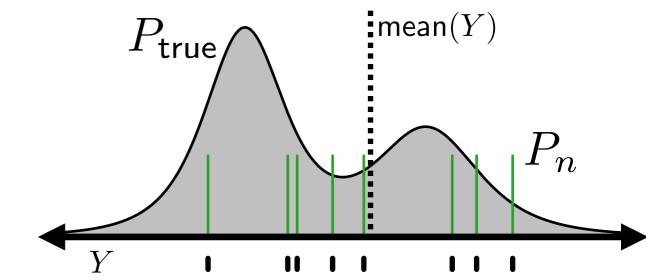
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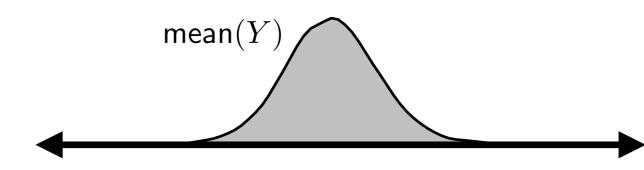
distribution of...



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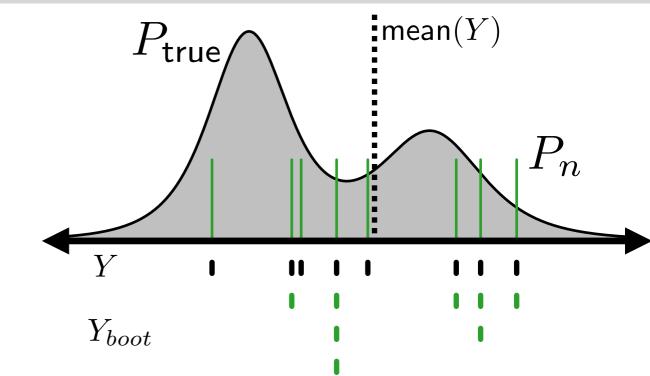


distribution of...

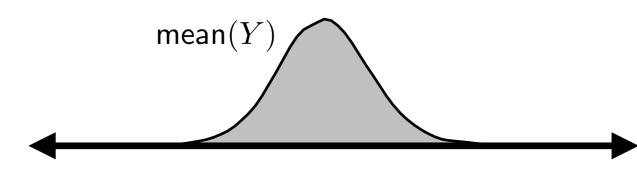


5

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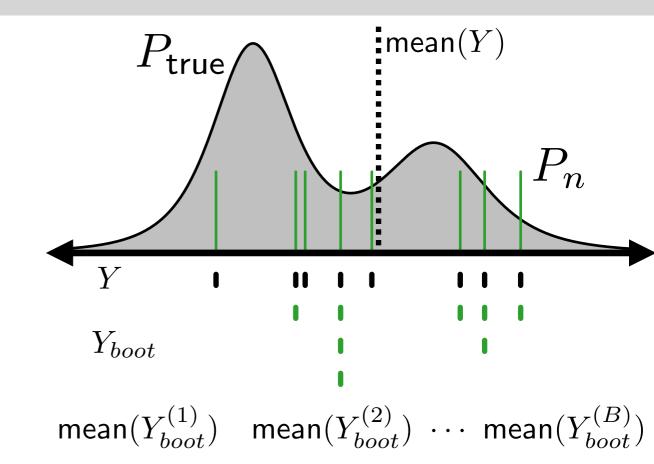


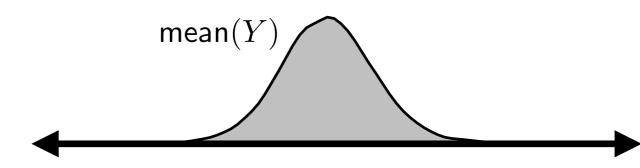
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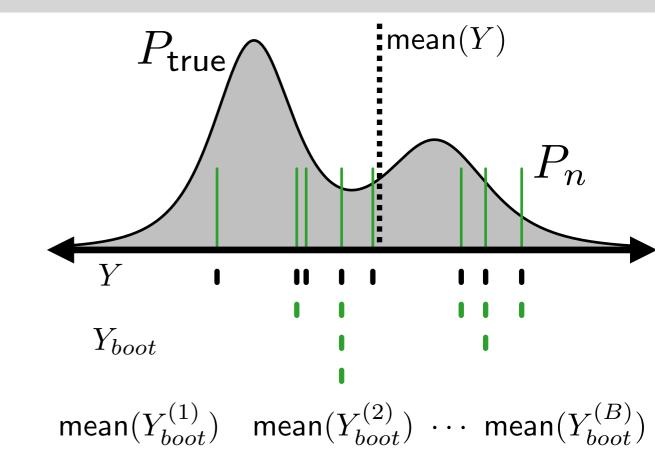
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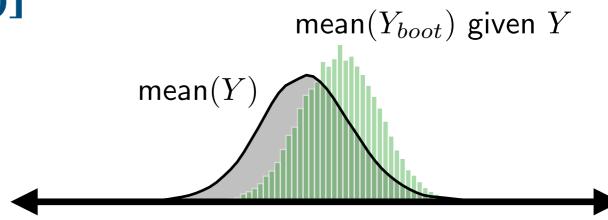
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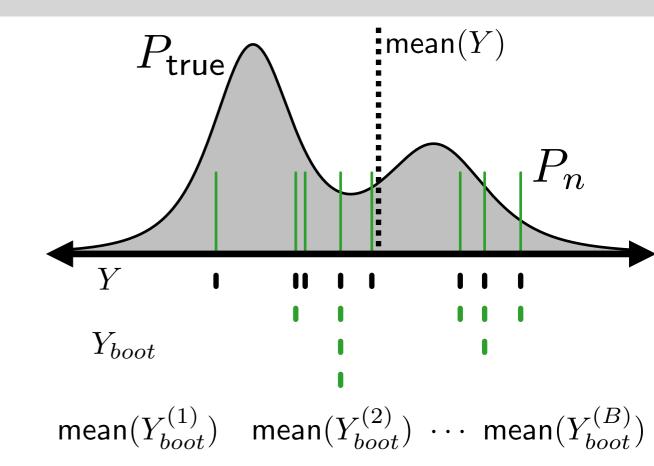


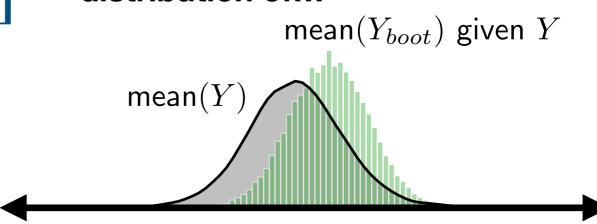
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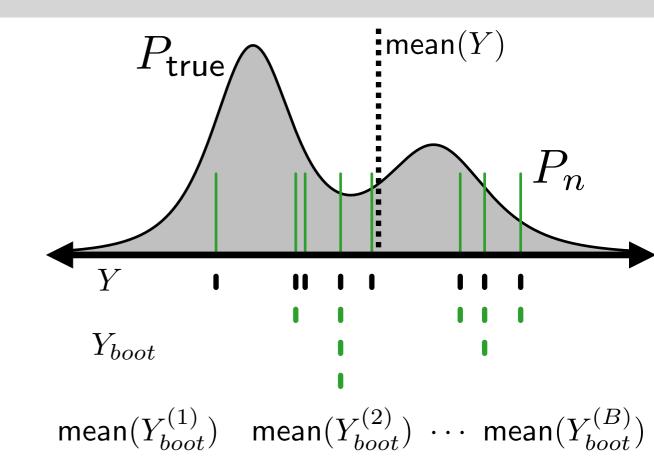


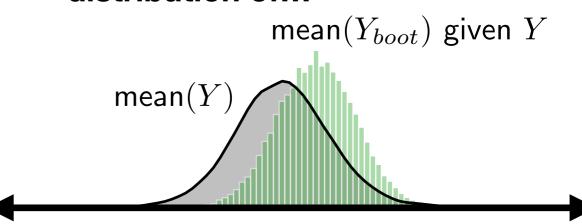
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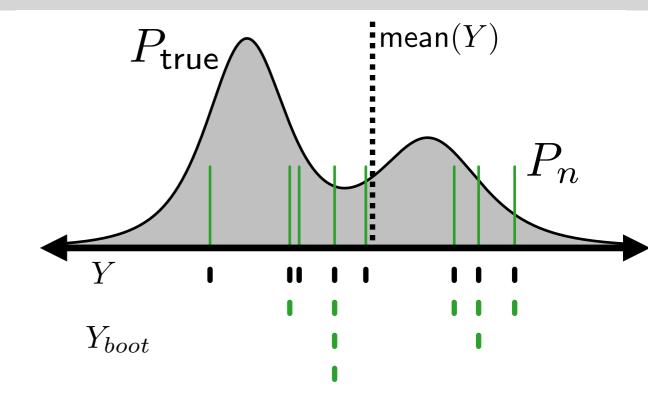




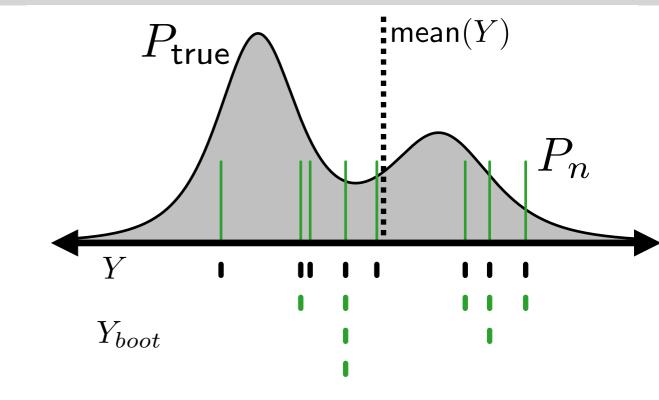
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- Challenges: *B* large (1,000-100,000), finite-sample properties

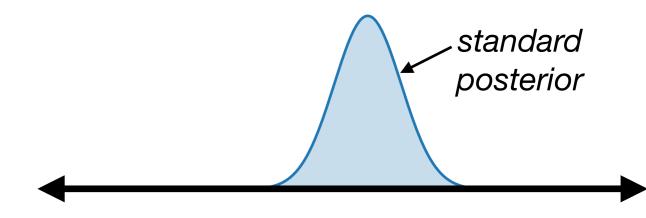






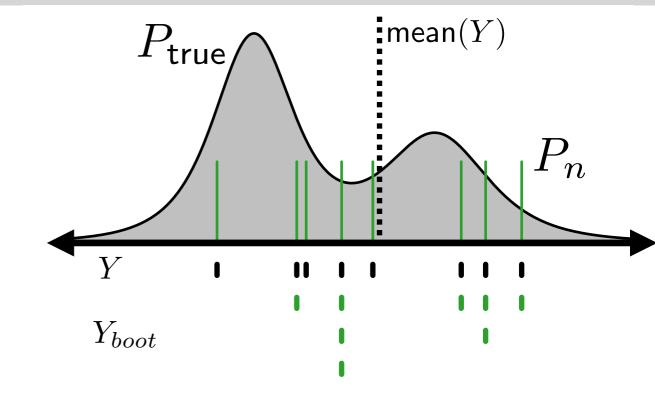
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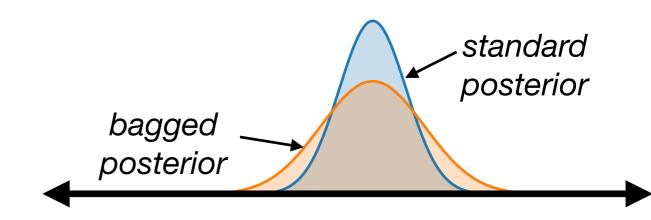




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$$\pi_{BB}(\theta \mid Y) = \frac{1}{B} \sum_{b=1}^{B} \pi(\theta \mid Y_{boot}^{(b)})$$

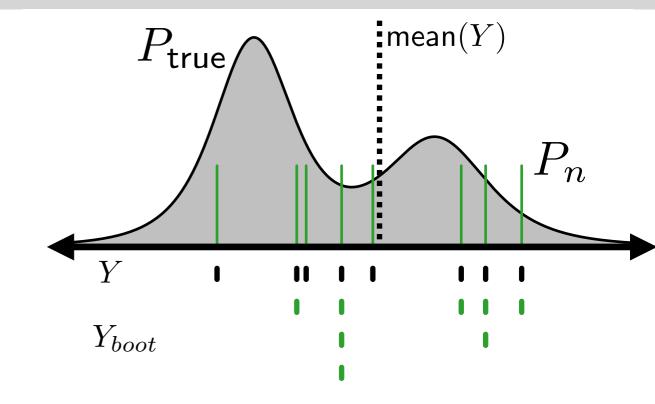


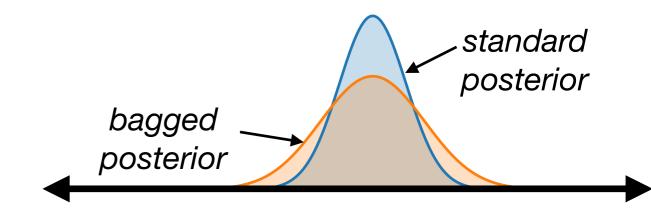


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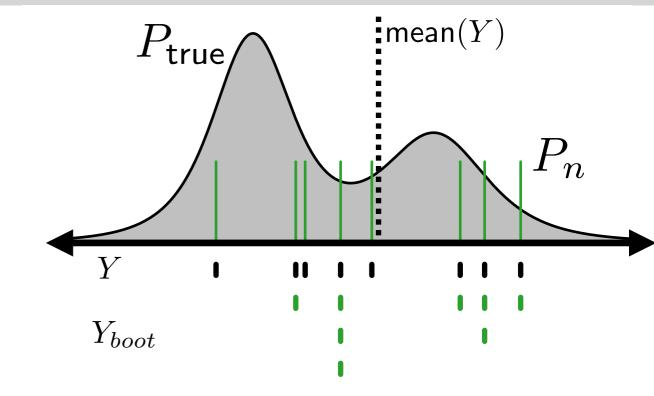


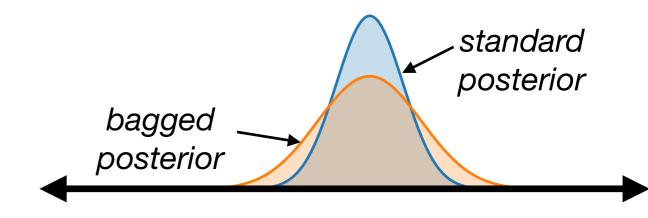


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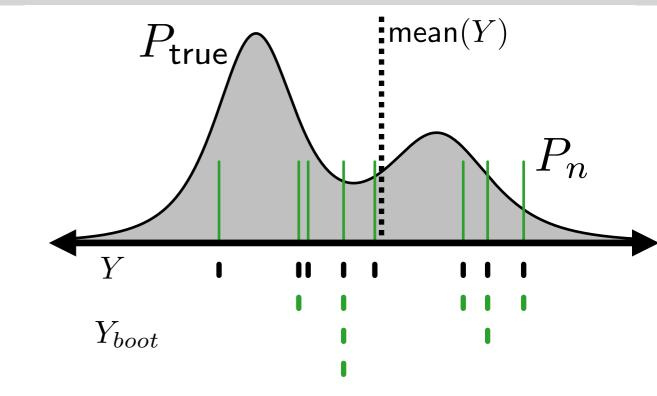


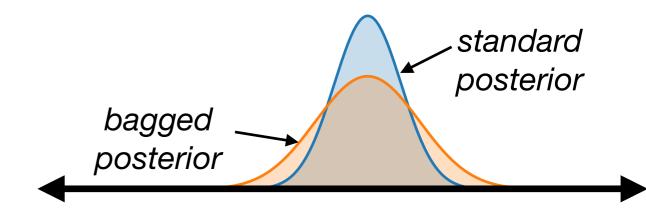


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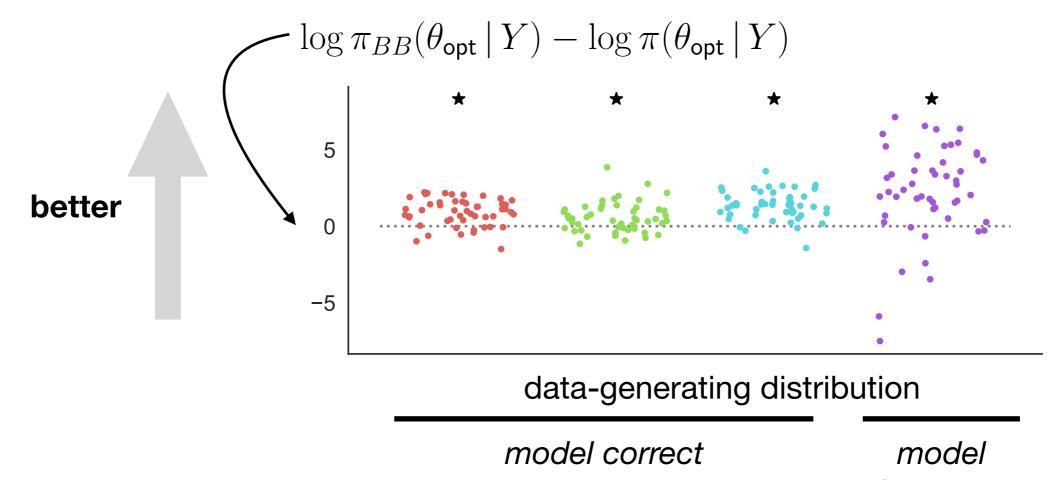
Better parameter inference with BayesBag

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- Performance metric is difference in log posterior density at θ_{opt} :

$$\log \pi_{BB}(\theta_{\mathsf{opt}} \mid Y) - \log \pi(\theta_{\mathsf{opt}} \mid Y)$$

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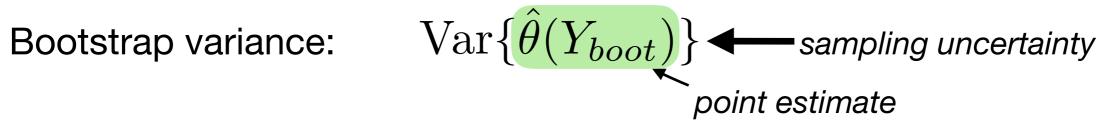
incorrect

Agenda

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Bootstrap variance: $\operatorname{Var}\{\hat{\theta}(Y_{boot})\}$

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 point estimate



Bootstrap variance: $Var\{\hat{\theta}(Y_{boot})\}$ \longrightarrow sampling uncertainty point estimate

Sample from posterior: $\,\vartheta \sim \pi(\theta \,|\, Y)\,$

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Posterior variance: $Var(\vartheta \mid Y)$

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Sample from posterior: $\vartheta \sim \pi(\theta \mid Y)$

Posterior variance: $Var(\vartheta | Y)$ — model-based uncertainty

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Sample from posterior: $\vartheta \sim \pi(\theta \mid Y)$

Posterior variance: $Var(\vartheta | Y)$ — model-based uncertainty

Sample from BayesBag posterior: $\vartheta_{BB} \sim \pi_{BB}(\theta \,|\, Y)$

Bootstrap variance: $\operatorname{Var}\{\hat{\theta}(Y_{boot})\}$ \longrightarrow sampling uncertainty point estimate

Sample from posterior: $\vartheta \sim \pi(\theta \mid Y)$

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BayesBag posterior variance:

$$Var(\vartheta_{BB} \mid Y)$$

Bootstrap variance: $\operatorname{Var}\{\hat{\theta}(Y_{boot})\}$ \longrightarrow sampling uncertainty point estimate

Sample from posterior: $\vartheta \sim \pi(\theta \mid Y)$

Posterior variance: $Var(\vartheta | Y)$ — model-based uncertainty

Sample from BayesBag posterior: $\vartheta_{BB} \sim \pi_{BB}(\theta \,|\, Y)$

BayesBag posterior variance:

$$Var(\vartheta_{BB} \mid Y) = \mathbb{E}\{Var(\vartheta_{BB} \mid Y_{boot})\} + Var\{\mathbb{E}(\vartheta_{BB} \mid Y_{boot})\}$$

Bootstrap variance: $\operatorname{Var}\{\hat{\theta}(Y_{boot})\}$ \longrightarrow sampling uncertainty point estimate

Sample from posterior: $\vartheta \sim \pi(\theta \mid Y)$

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expected posterior variance

Bootstrap variance: $Var\{\hat{\theta}(Y_{boot})\}$ \longrightarrow sampling uncertainty point estimate

Sample from posterior: $\,\vartheta \sim \pi(\theta \,|\, Y)\,$

Posterior variance: $Var(\vartheta | Y)$ model-based uncertainty

BayesBag posterior variance:

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expected posterior variance

variance of posterior mean

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point estimate

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Bootstrap variance: point estimate Sample from posterior: $\vartheta \sim \pi(\theta \mid Y)$ $Var(\vartheta | Y)$ model-based uncertainty Posterior variance: Sample from BayesBag posterior: $V_{BB} \sim \pi_{BB}(\theta \,|\, Y)$ BayesBag posterior variance: point estimate $\operatorname{Var}(\vartheta_{BB} \mid Y) = \mathbb{E}\left\{ \operatorname{Var}(\vartheta_{BB} \mid Y_{boot}) \right\} + \operatorname{Var}\left\{ \mathbb{E}(\vartheta_{BB} \mid Y_{boot}) \right\}$ variance of expected posterior

variance

posterior mean

Summarizing the previous slide...

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Posterior variance = *model-based uncertainty*

Summarizing the previous slide...

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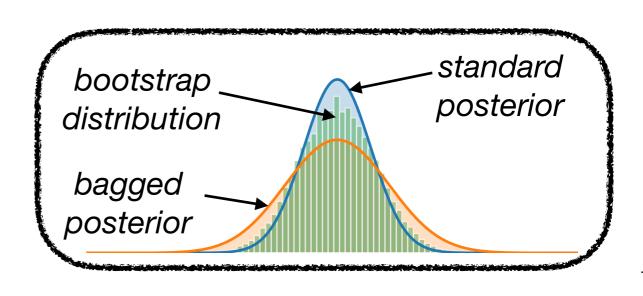
BayesBag variance = model-based + sampling-based uncertainty

Summarizing the previous slide...

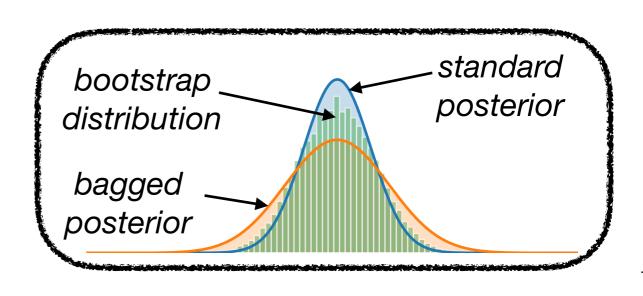
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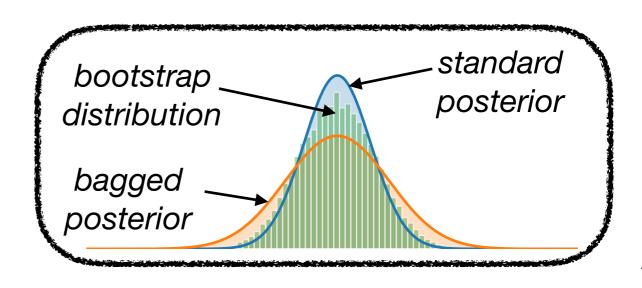
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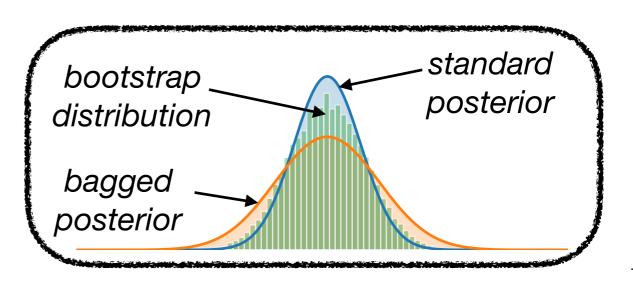
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- Model correct: model-based uncertainty = sampling-based uncertainty



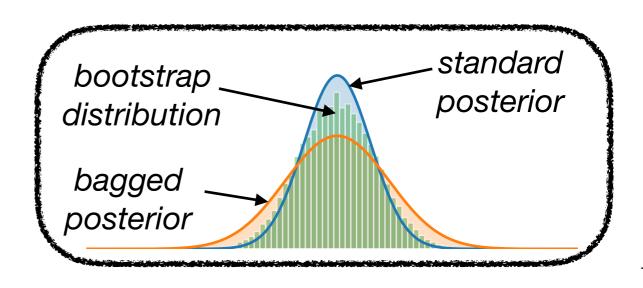
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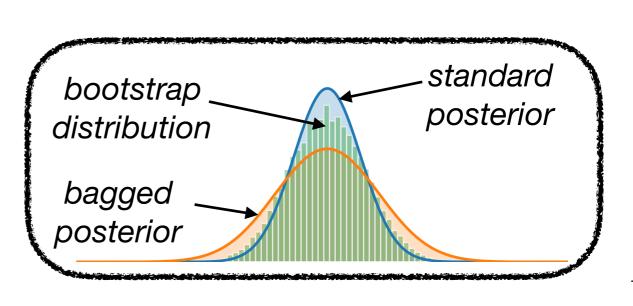
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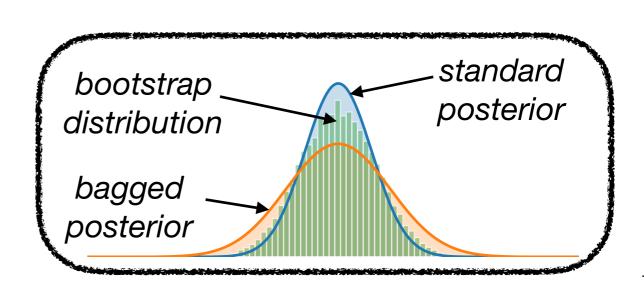
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- Model incorrect: *model-based uncertainty* « *sampling-based uncertainty*
 - Posterior variance far too small



- Summarizing the previous slide...
 - Posterior variance = *model-based uncertainty*
 - Bootstrap variance = *sampling-based uncertainty*
 - BayesBag variance = model-based + sampling-based uncertainty
- Model correct: model-based uncertainty = sampling-based uncertainty
 - Posterior and bootstrap variances correct
 - BayesBag variance double-counts true uncertainty (conservative)
- Model incorrect: model-based uncertainty « sampling-based uncertainty
 - Posterior variance far too small
 - BayesBag variance appropriately calibrated



Posterior variance = model-based uncertainty

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[**H** & Miller 2019]

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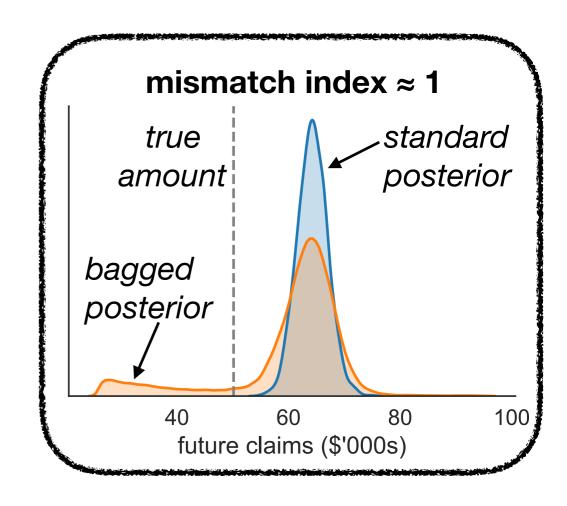
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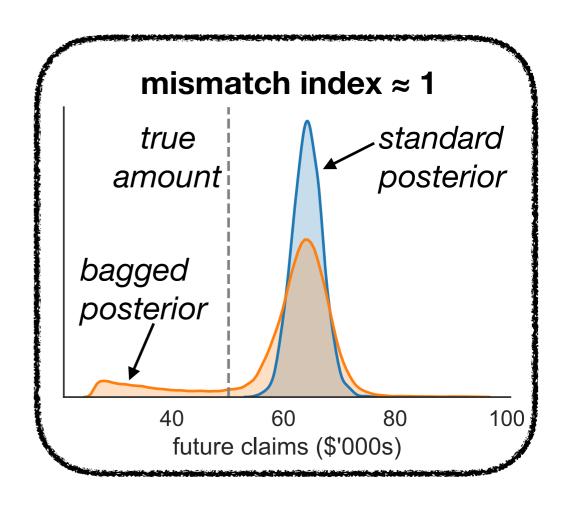


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- Model criticism: mismatch index indicates when model needs improvement

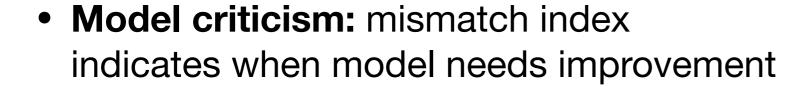


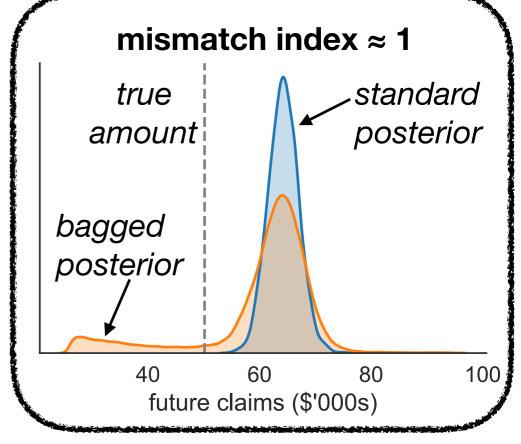
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Mismatch index can also detect problems with the prior

[**H** & Miller 2019]

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12

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- 4) output bagged posterior computed in step 2

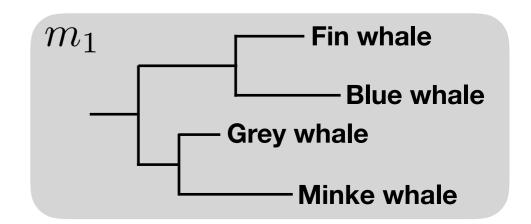
Agenda

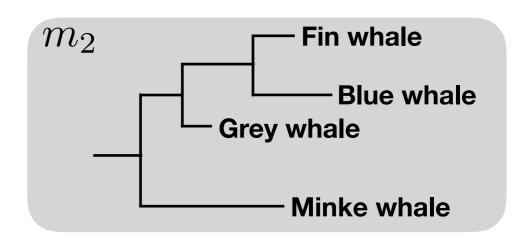
- BayesBag for parameter inference (and prediction)
- BayesBag theory and methodology
- BayesBag for model selection

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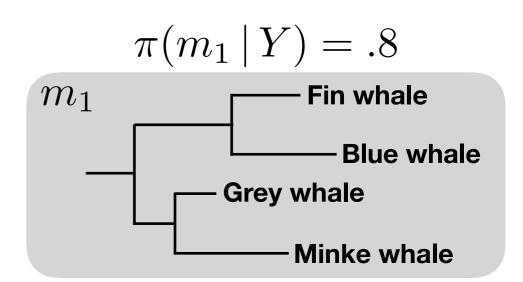
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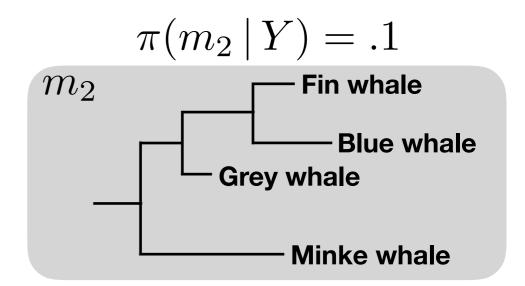




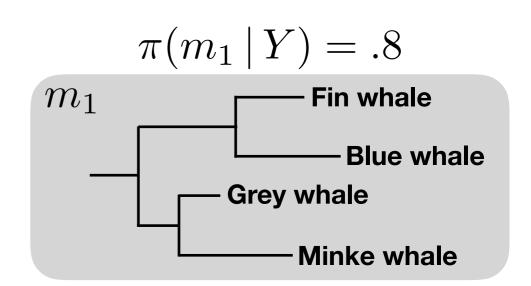
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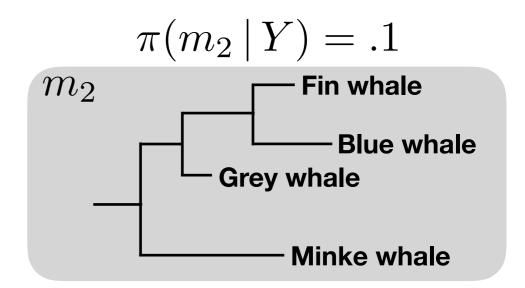
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- Problem: Bayesian model selection still assumes some model in M is correct

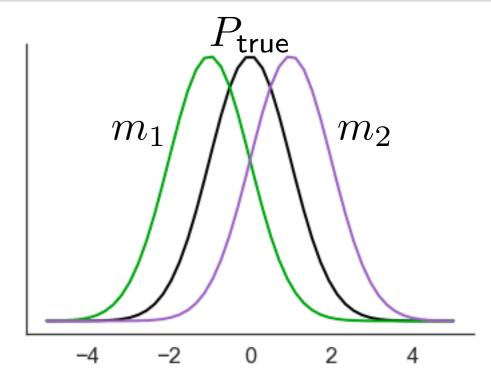




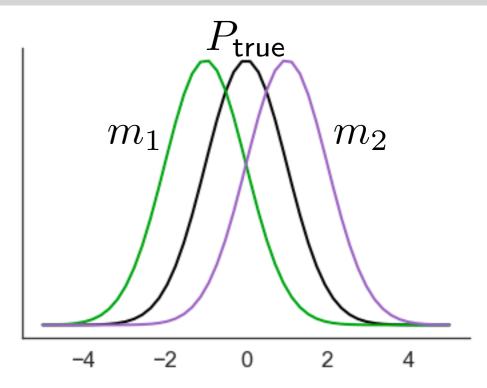
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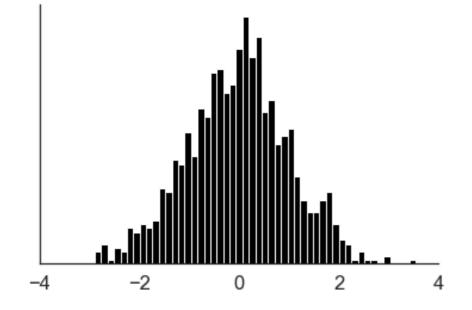


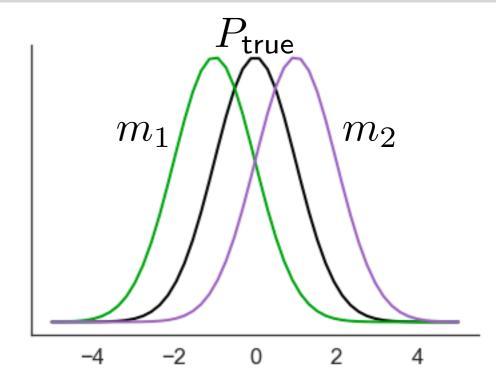
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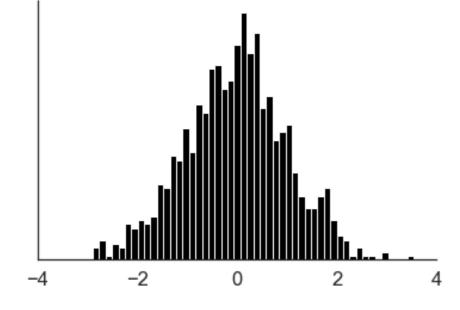
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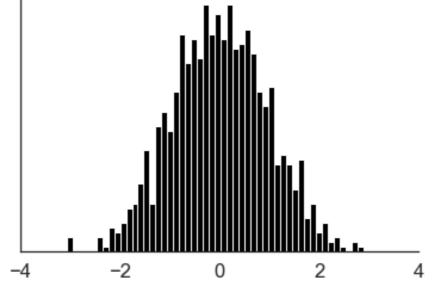


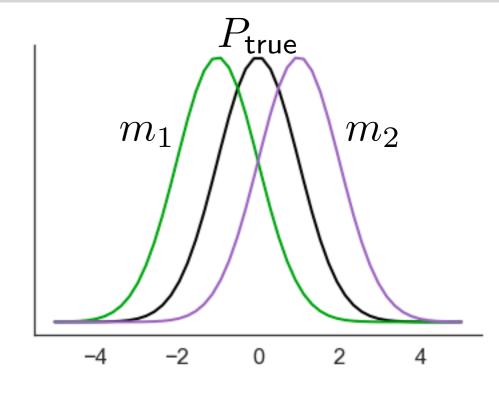


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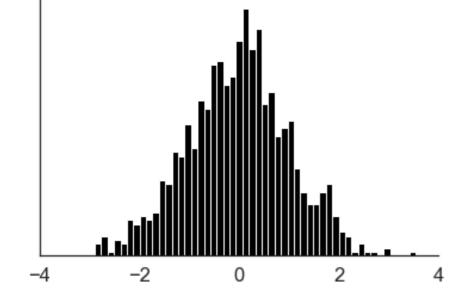


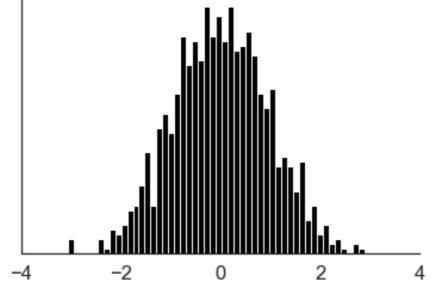


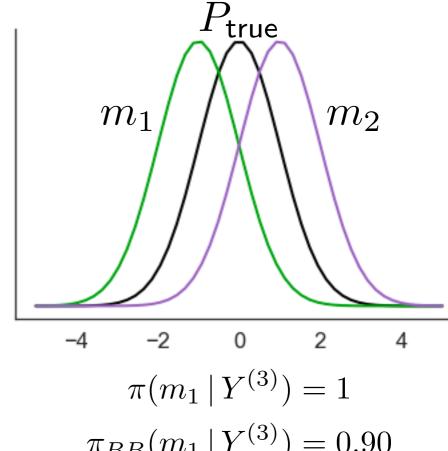
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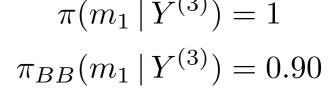
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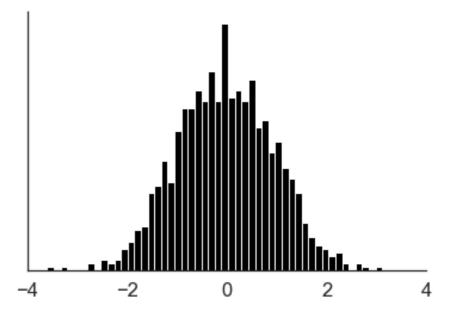
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 $\pi_{BB}(m_1 | Y^{(2)}) = 0.38$











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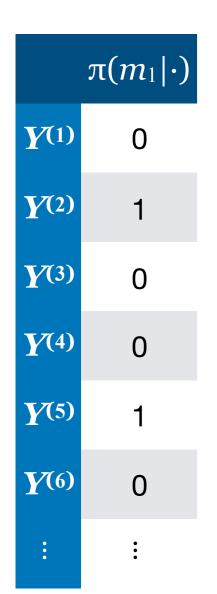
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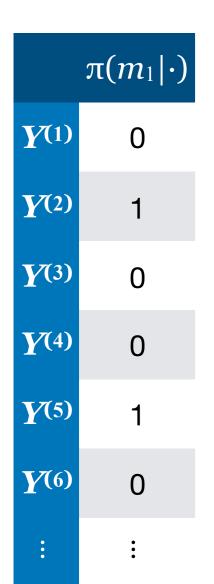
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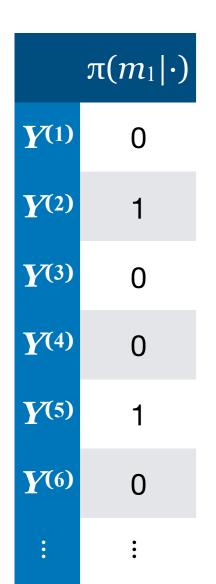
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Y (2)	1	0.78
Y (3)	0	0.75
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BayesBag stabilizes posterior probabilities of similar models

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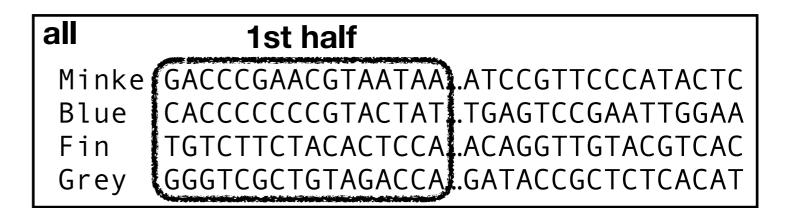
bagged posterior mass more evenly distributed

[**H** & Miller 2019]

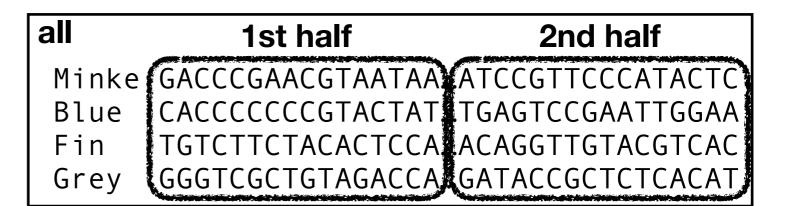
 Goal: infer phylogeny of 13 whale species from mitochondrial coding DNA

Minke GACCCGAACGTAATAA...ATCCGTTCCCATACTC Blue CACCCCCCGTACTAT...TGAGTCCGAATTGGAA Fin TGTCTTCTACACTCCA...ACAGGTTGTACGTCAC Grey GGGTCGCTGTAGACCA...GATACCGCTCTCACAT

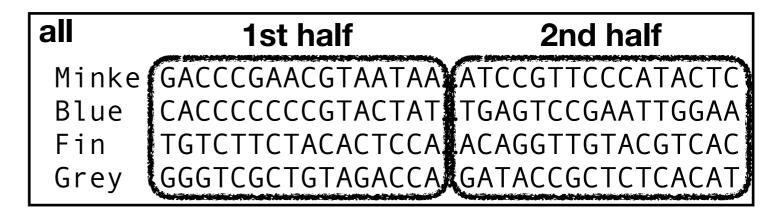
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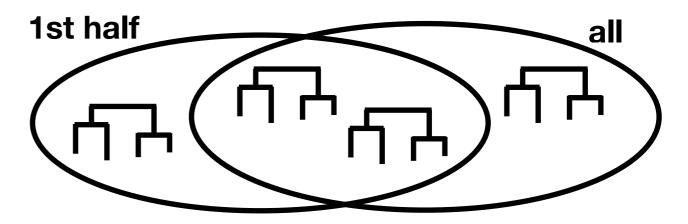


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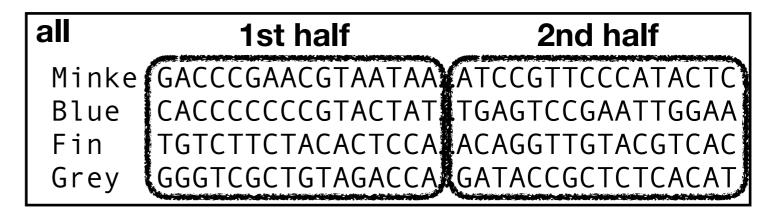


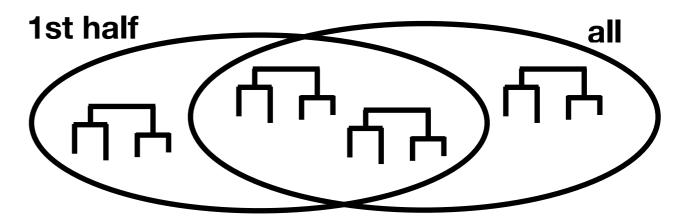
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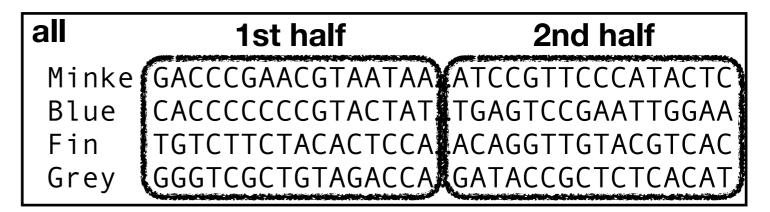


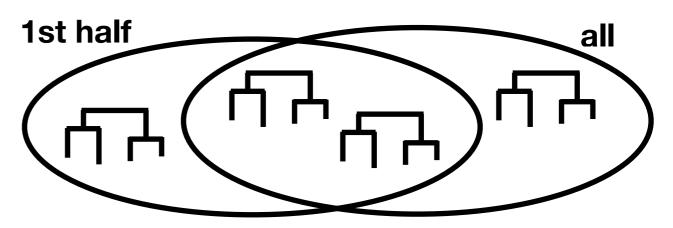
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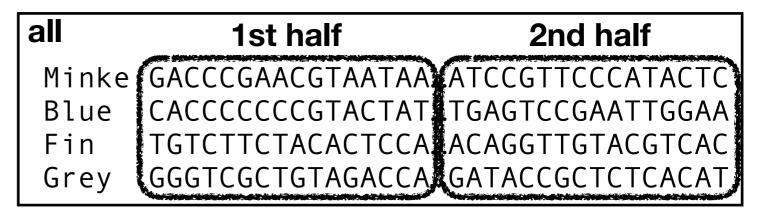


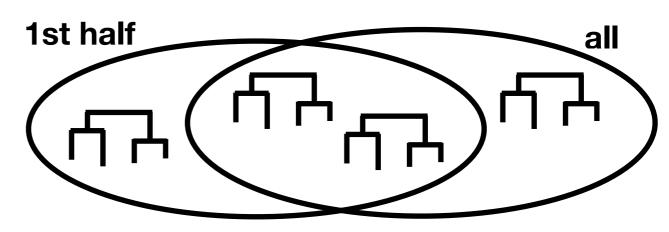
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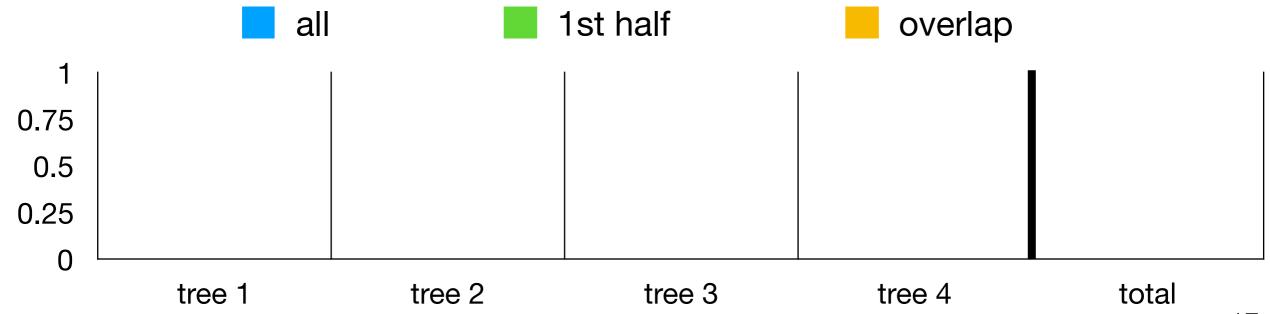




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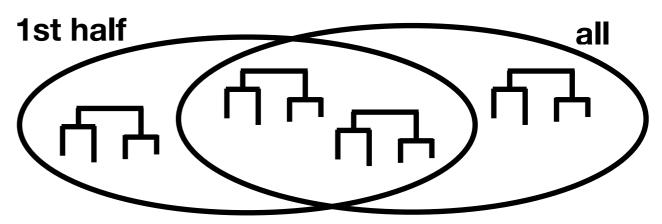


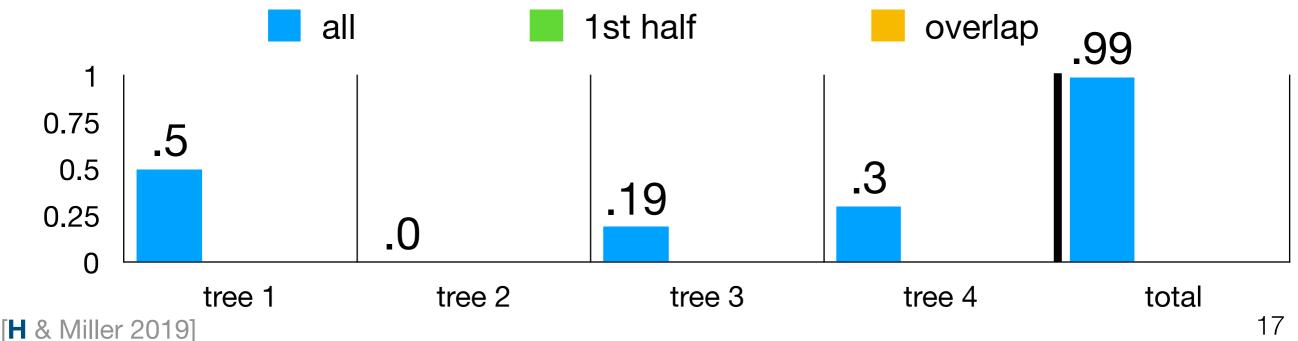




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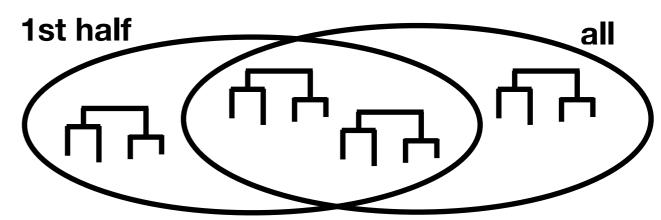


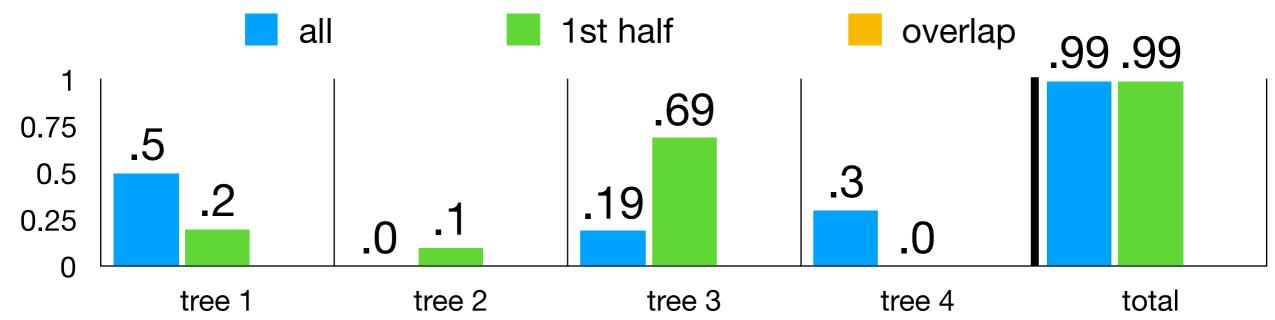




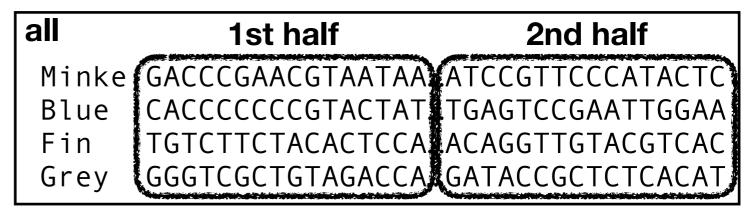
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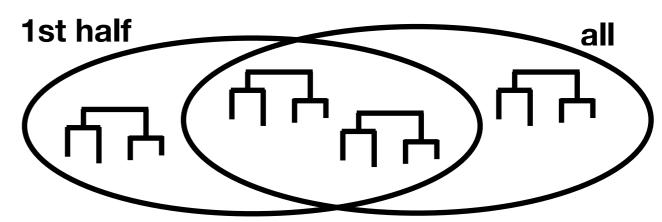


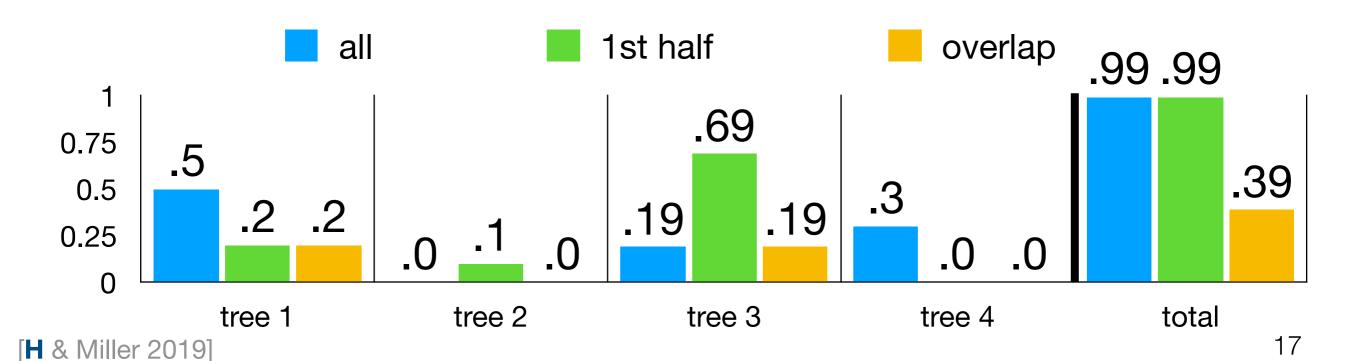




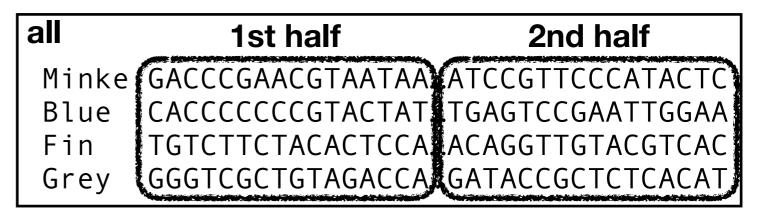
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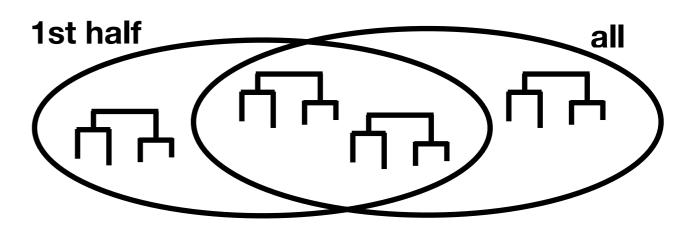


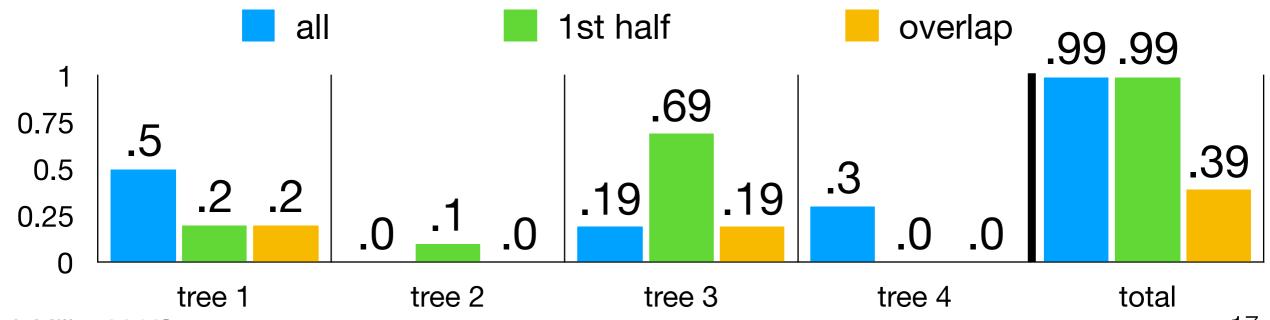




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- 0% overlap = contradiction

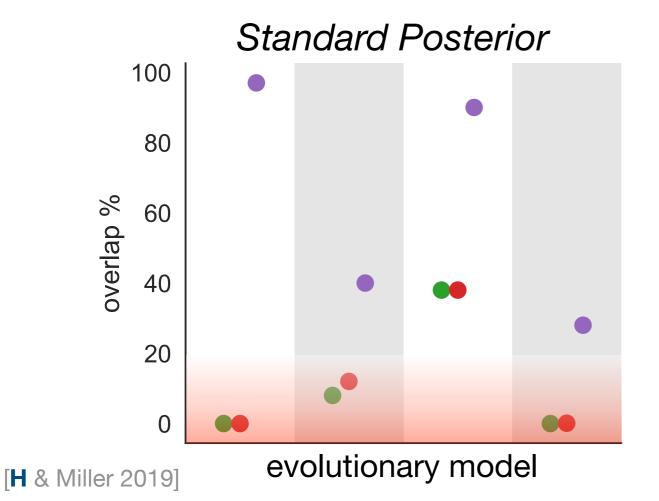


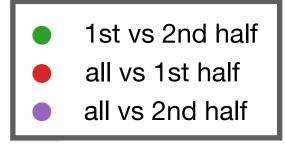




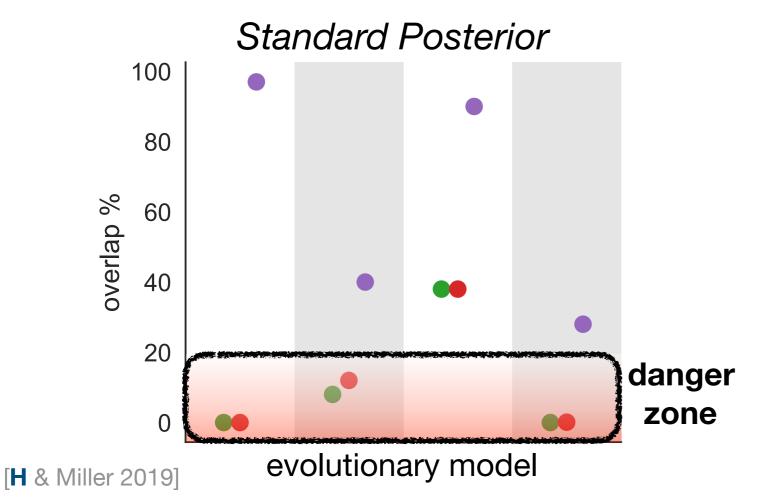
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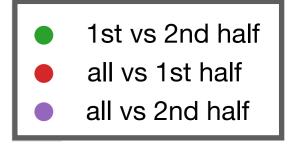
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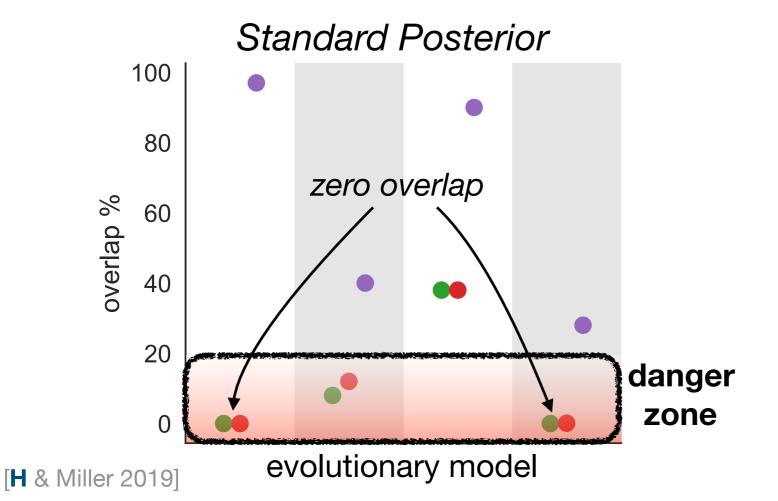


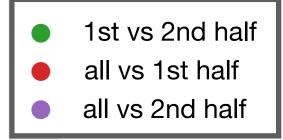
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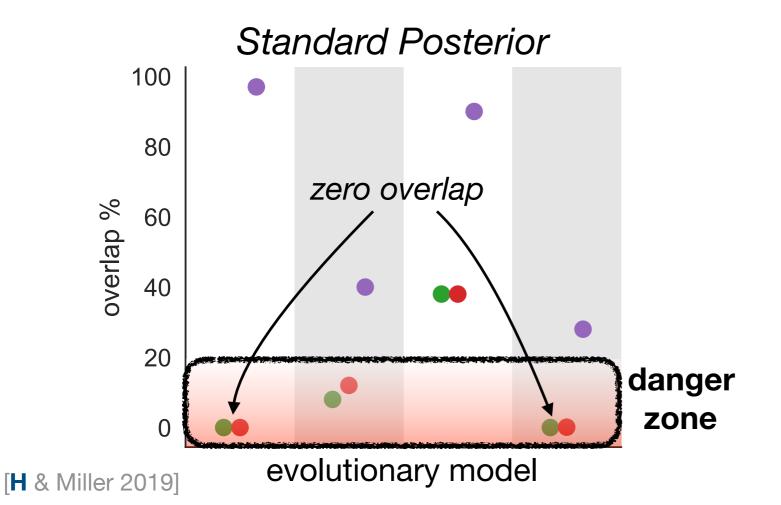


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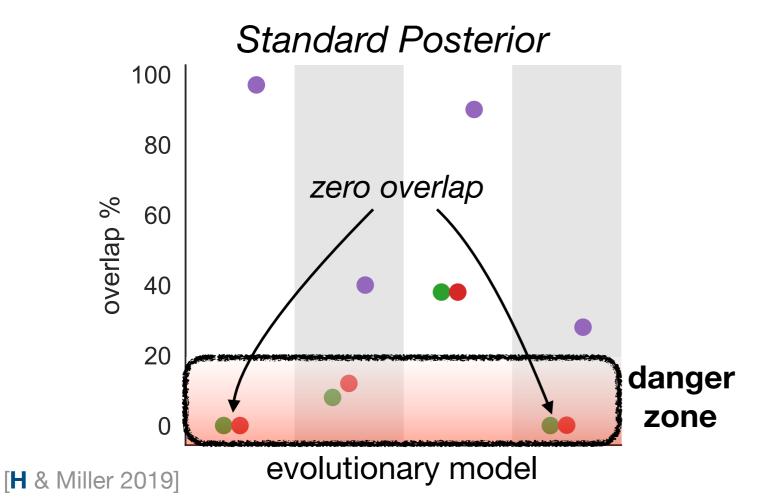


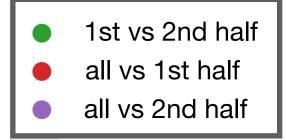
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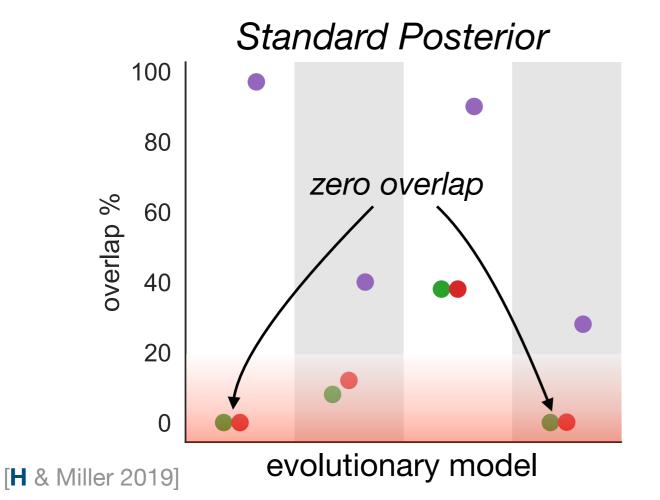


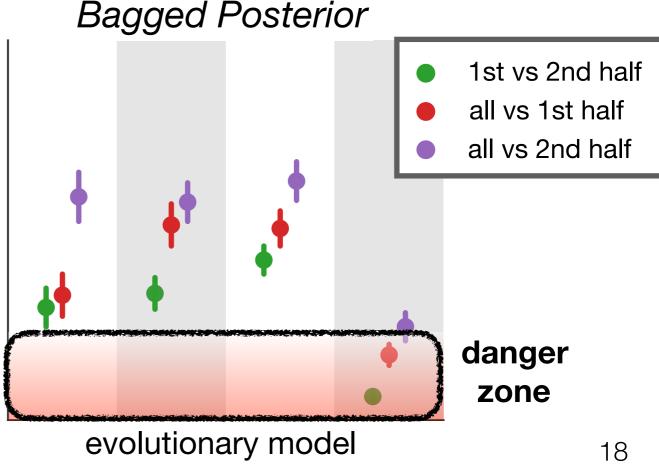
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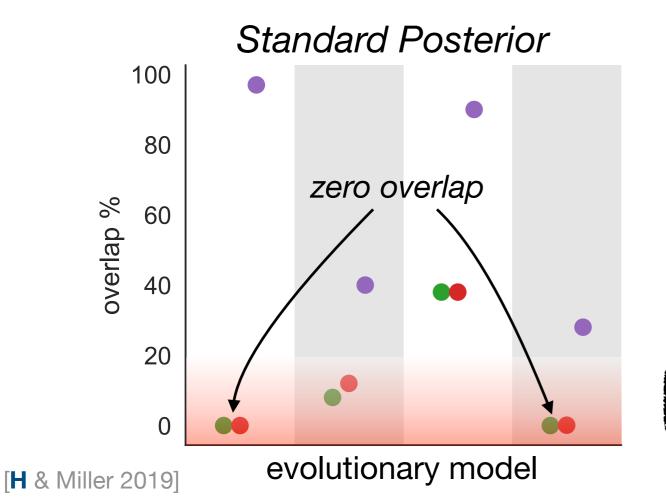


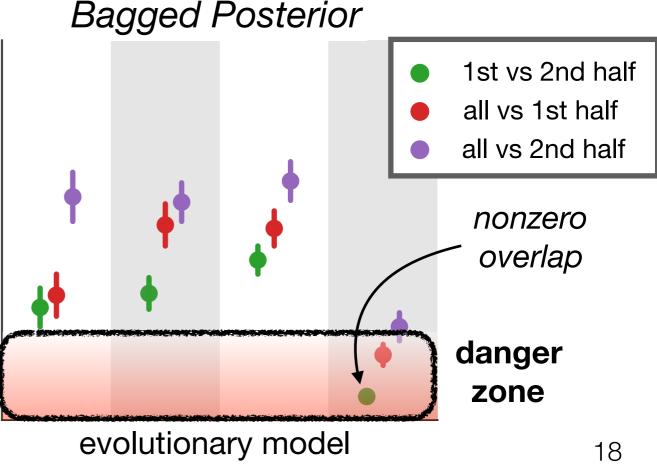
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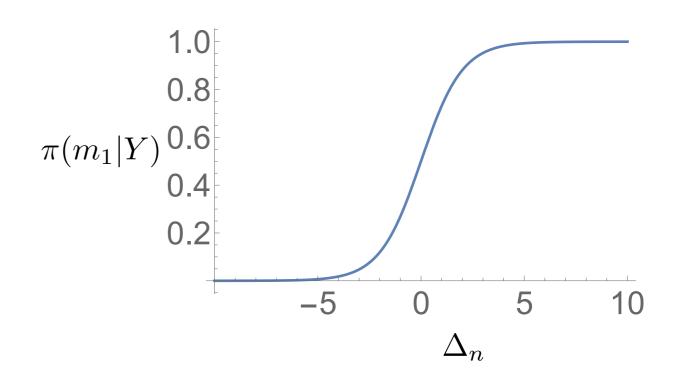
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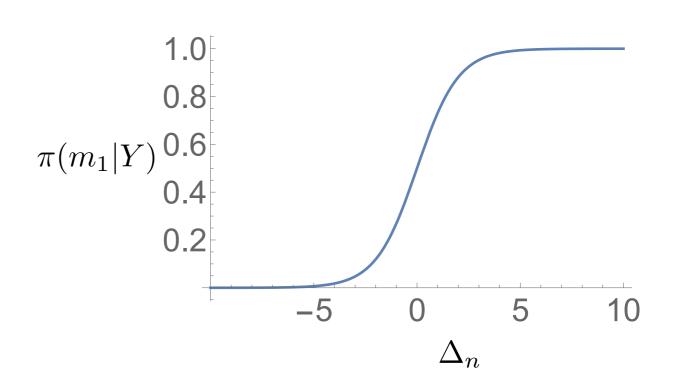
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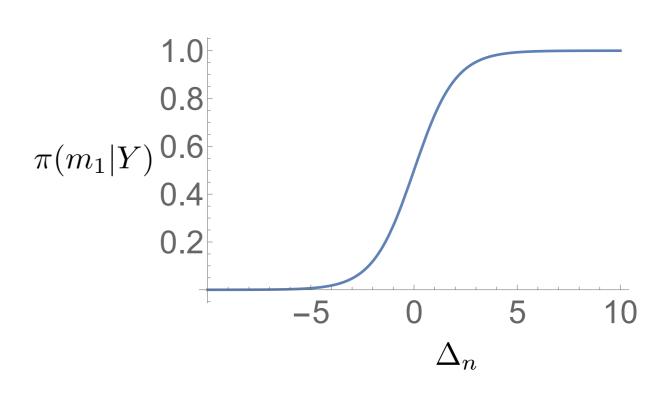
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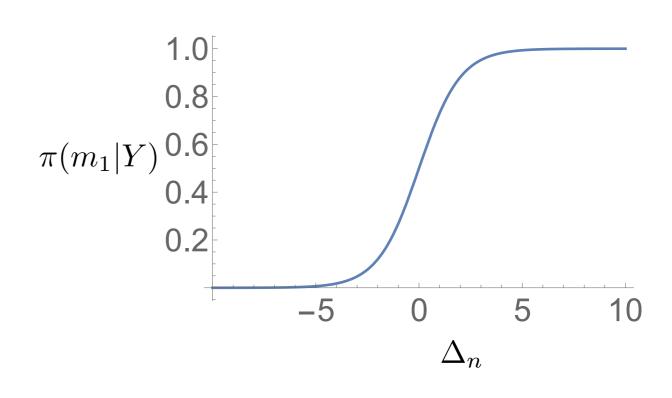
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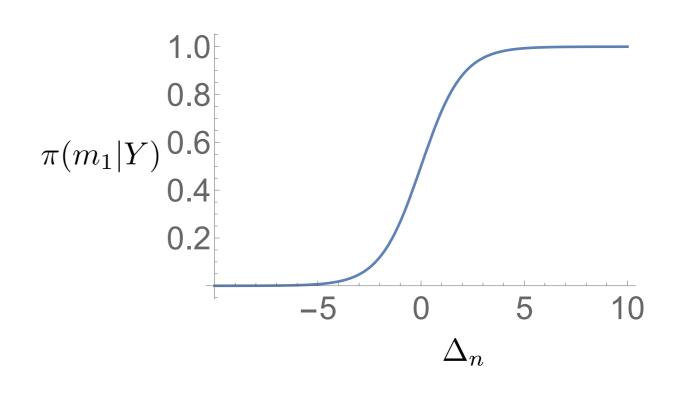
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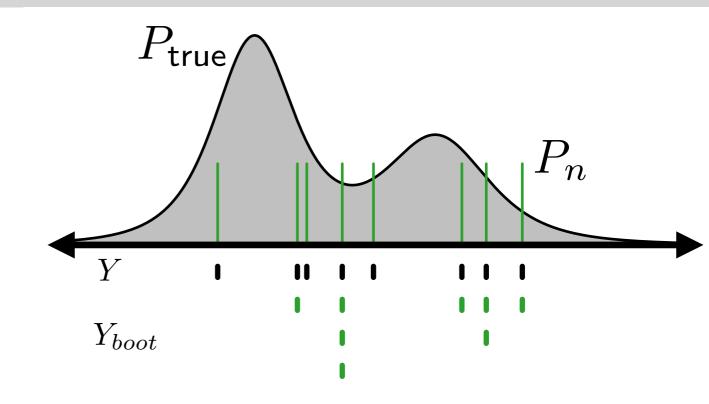
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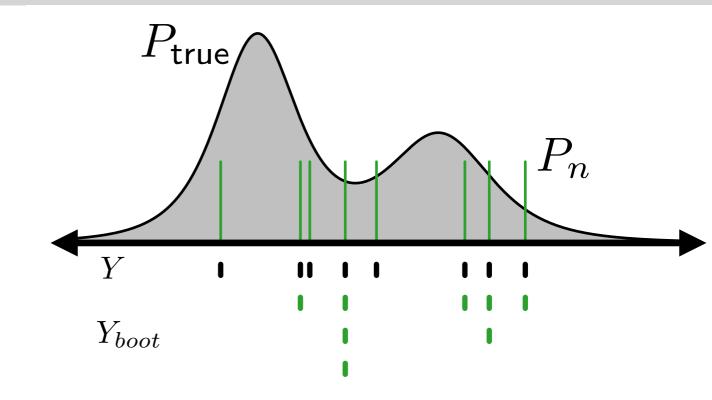
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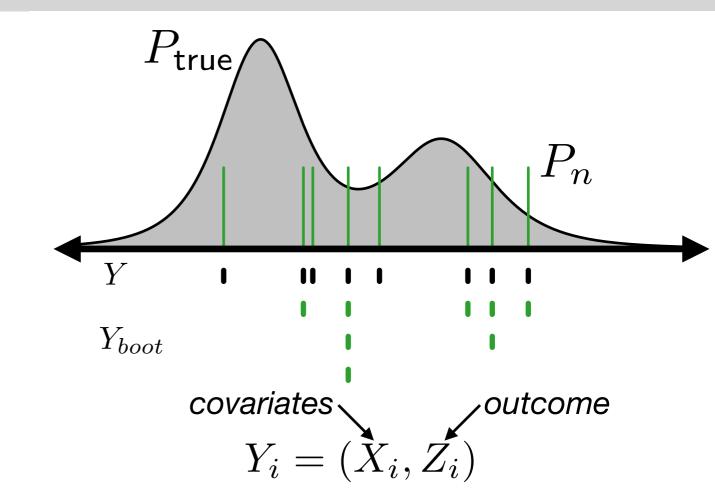
ullet Therefore, there is overwhelming evidence of order $n^{1/2}$ for either m_1 or m_2



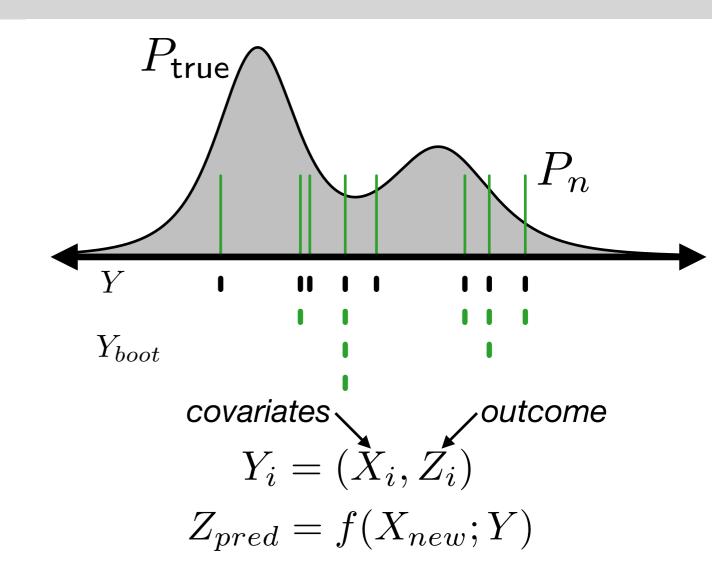
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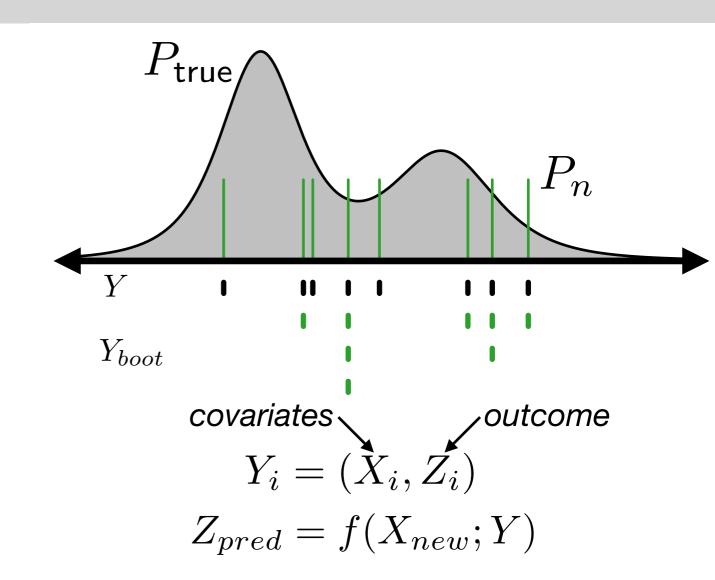
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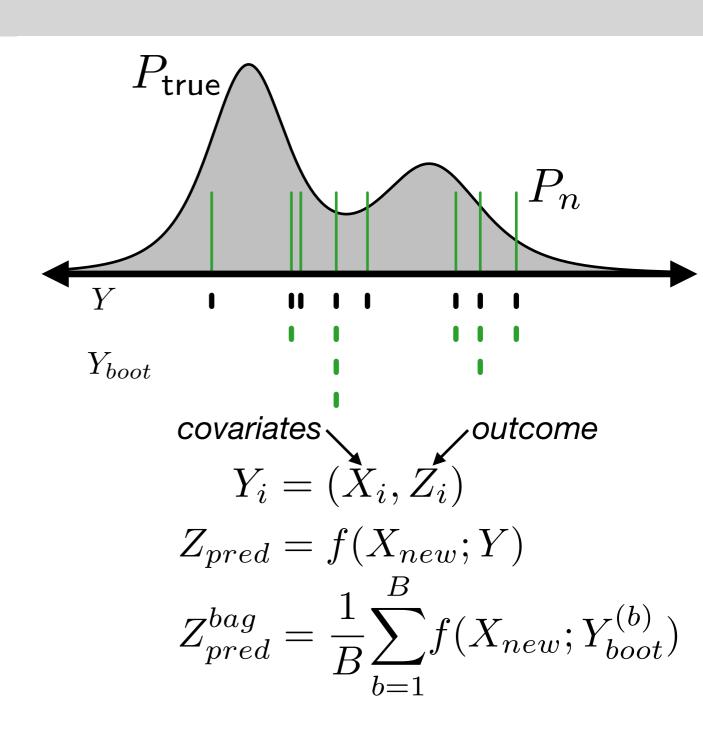
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- Like bagging, BayesBag seems to work well with B = 50 or 100

